Optoelectronic delayed-feedback and chaos in quantum-well laser diodes

C. Juang a,*, C.C. Huang b, T.M. Hwang c, J. Juang d, W.W. Lin b

a Department of Electronics, Ming Hsin College, Hsinfeng, Hsinchu, Taiwan, ROC
b Department of Mathematics, National Tsing Hua University, Hsinchu, Taiwan, ROC
c Department of Applied Mathematics, I-Shou University, Kaohsiung, Taiwan, ROC
d Department of Applied Mathematics, National Chiao Tung University, Hsinchu, Taiwan, ROC

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Abstract

Electronic-controlled route to chaos in a quantum-well laser diode is carried out by a delayed-feedback technique. By introducing an extra delayed-feedback control term $cS_n(t - \tau)$, chaotic light output can be achieved at relatively low bias and small modulation depth. Bifurcation diagram, Poincaré map, and Lyapunov exponents suggest quasi-periodicity route to chaos. © 2001 Elsevier Science B.V. All rights reserved.

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Dynamical chaos in laser diodes has become an interesting topic due to its potential application in private communication [1,2]. Chaotic light output from a laser diode can be achieved by optical-or electronic-controlled techniques. Optical-controlled technique includes optical feedback using an external cavity [3] or by an optical injection from a second laser diode [4]. Electronic-controlled technique is carried out by injecting a sinusoidal and a bias current into the laser diode $I = a + b \sin 2\pi f_0 t$, where $a$ is the bias current, $b$ is the modulation current, $f_0$ is the external modulation frequency [5,6]. In general, high bias and strong current modulation, or two tone modulation are required to achieve chaos.

Electronic-controlled route to chaos in a laser diode can be further expanded using a delayed-feedback technique. This delay technique has also been used to optical-controlled route to chaos in a laser diode [7]. Hopf bifurcation subject to a large delay is also verified [8]. In this work, the electronic delayed-feedback technique is applied to a quantum-well laser diode. A PIN photodetector can be placed at the other side of the facet of the laser diode, as the case of most commercial laser diodes. The photocurrent is proportional to the output photon density $S_n(t)$. Since the chaotic output is always a broadband signal, the bandwidth of the photodetector should be high enough to ensure the coverage of the chaotic spectra. An electronic

*Corresponding author. Fax: +886-3-559-1402.
E-mail address: cjuang@mhit.edu.tw (C. Juang).
delayed-feedback loop is then established by leading the photocurrent to a delayed-time circuit and a gain stage, and then mixing with the sinusoidal input, as illustrated in Fig. 1. The overall current is then injected into the laser diode and is given by

\[ I = a + b \sin 2\pi f_0 t + c S_n(t - \tau), \]

where \( a \) is the current gain, and \( \tau \) is the loop delay time. With the introduction of the extra delay term \( c S_n(t - \tau) \), it is shown that the chaotic light output can be obtained at relatively low bias and small modulation depth. Note that without modulation and delay, the system always converges to a fixed point. With delay only or small modulation depth only, it is not possible to achieve chaos. The interaction between modulation and delay forms a quasi-two-period route to chaos. These chaotic behaviors are further investigated by bifurcation diagram, Poincaré map, and Lyapunov exponent.

The three-dimensional quantum-well rate equation to describe the dynamics of carrier in separate confinement regions \( I_s \), in quantum well region \( I_n \), and photon density \( S_n \) using the delayed-feedback technique is given by [9]

\[ \tau_s \frac{dI_s}{dt} = a + b \sin 2\pi f_0 t + c S_n(t - \tau) - \left( \frac{1}{\tau_n} + \frac{1}{\tau_s} \right) I_s, \]

\[ \tau_n \frac{dI_n}{dt} = I_s - I_n - \frac{G}{1 - \epsilon_n} S_n, \]

\[ \frac{C_p}{T} \frac{dS_n}{dt} = G(1 - \epsilon_n S_n) S_n + \beta I_n - \frac{S_n}{TR_p}, \]

where \( \tau_s \) is the carrier transport time across separate confinement heterostructure regions, \( \tau_n \) is the bimolecular recombination lifetime, \( T \) is the optical confinement factor per well, \( \beta \) is the spontaneous emission factor, and \( \epsilon \) is the gain compression factor. In addition, the optical gain function is expressed by a square dependence on the recombination current \( J_{\text{nom}} \) [10], \( G = D(J_{\text{nom}} - 2 \times 10^{13})^2 \), where \( D \) is a constant, \( J_{\text{nom}} = I_n/V_a \), and \( V_a \) is the active layers volume. Table 1 lists all the parameters of the QW laser diode used in the simulation. Without feedback and modulation \( (b = c = 0) \), \( L-I \) curve simulation suggests a threshold current \( I_{\text{th}} \) of 38 mA. This agrees with a simple steady state analysis, in which the threshold current can be approximated as \( (1 + \tau_s/\tau_n)(V_a N_0 + V_a/\sqrt{BR_p D}) \). The step-response simulation (switching from 0 to \( a \), where \( a = 1.5 I_{\text{th}} \)) results in a relaxation oscillation \( f_r \) of 2.12 GHz and a period \( T \) of 0.471 ns.

To solve the delay differential equations, Eq. (2) can be expressed as \( \dot{X} = F(t, X) + A(t, X) \), where \( X \in R^3 \) is the state variable \( X = (X^1, X^2, X^3) \), \( F = R \times R^3 \rightarrow R^3 \) as a nonlinear function, and \( A \in M^3 \times 3 \) is a matrix with a nonzero term at \( a_{13} \) from Eq. (2). By modifying the fourth-order Runge–Kutta–Fehlberg method (RK45) [11] for fixed time step \( A(= \tau/n) \), we have

\[ \dot{X}_m = \varphi(X_{m-1}, X_{m-n}) \]

\[ = X_{m-1} + \sum_{i=0}^{5} c_i F_i^m, \]

where

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Value</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \tau_s )</td>
<td>6</td>
<td>ps</td>
</tr>
<tr>
<td>( \tau_n )</td>
<td>2.25</td>
<td>ns</td>
</tr>
<tr>
<td>( \epsilon )</td>
<td>( 10^{-17} )</td>
<td>cm³</td>
</tr>
<tr>
<td>( T )</td>
<td>0.2</td>
<td></td>
</tr>
<tr>
<td>( R_p )</td>
<td>59.5</td>
<td>Ω</td>
</tr>
<tr>
<td>( C_p )</td>
<td>0.0489</td>
<td>μf</td>
</tr>
<tr>
<td>( \beta )</td>
<td>( 10^{-4} )</td>
<td></td>
</tr>
<tr>
<td>( D )</td>
<td>( 1.79 \times 10^{-20} )</td>
<td>V⁻¹ A⁻¹ m²</td>
</tr>
<tr>
<td>( qV_a )</td>
<td>( 6.85 \times 10^{-35} )</td>
<td>m³ C</td>
</tr>
</tbody>
</table>
\[ F^m_0 = \mathcal{F}(mA, x_{m-1}) + AX_{m-n}, \]
\[ F^m_i = \mathcal{F}\left(mA + q_i, x_{m-1} + \sum_{j=0}^{i-1} h_{ij} F^m_j\right) + A\left[\frac{A - q_i}{A} x_{m-n} + \frac{q_i}{A} x_{m-n+1}\right], \]  

and \( m \) is the time-step index \((m \geq n)\), and \( c, q_i \) and \( h_{ij} \) are the coefficients of the RK45 [11].

Fig. 2 shows the bifurcation diagram with \( S_n \) versus \( b \) when \( a = 1.5I_0, \tau = 0.75T, c = 0.035, \) and \( f_0 = 1/2f_i \). In the three-dimensional phase diagram \((I_s, I_n, S_n)\) of the rate equations, let \( S \) be a two-dimensional hyperplane through a point \((0.05, 0.0377, 0.4)\) with normal direction \([0, 1, 0]\). If the trajectory in the phase diagram mapped on the hyperplane densely fills out closed curve, then the solution forms a quasi-two-periodic orbit. When \( b \in (0, 3.5) \) the system has a quasi-two-period attractor. When \( b \) varies from 0.41 to 0.45, the effects of quasi-periodicity route to chaos are observed.

Fig. 3a and b shows Poincaré maps at \( b = 0.2 \) and 0.44. When \( b = 0 \), the system has an asymptotically stable fixed point. As \( b \) increases to 0.2, the fixed point expands into an invariant closed-loop circle, a set like a circle which captures the point of a solution sequence. When \( b = 0.44 \), the circle breaks up into a complicated attracting set. These behaviors characterize the quasi-period and chaos in the system.

![Fig. 2. Bifurcation diagram with \( S_n \) versus \( b \) when \( a = 1.5I_0, \tau = 0.75T, c = 0.035, \) and \( f_0 = 1/2f_i \).](image)

![Fig. 3. (a,b) Poincaré maps at \( b = 0.2 \) and \( b = 0.44 \) when \( a = 1.5I_0, \tau = 0.75T, c = 0.035, \) and \( f_0 = 1/2f_i \).](image)

Lyapunov exponents are the generalization of the eigenvalues at an equilibrium point of characteristic multipliers. They can be used to determine the stability of quasi-periodic and chaotic behaviors, as well as that of equilibrium points and periodic solutions. Following the Farmer’s approach [12], a detailed formation to calculate the Lyapunov exponents for the delay differential equation are described by

\[ \beta_i = \lim_{m \to \infty} \frac{1}{m} \ln |p_i(t)|, \]  

(5)
where \( p_i(t) \) is the \( i \)th eigenvalue of the Jacobian of \( G^m(\mathcal{Y}_0) \). And,

\[
\mathcal{Y}_m = \begin{pmatrix}
    \mathcal{X}_m \\
    \vdots \\
    \mathcal{X}_{m+n-1}
\end{pmatrix} = \begin{pmatrix}
    0 & I & \cdots & \cdots & 0 \\
    \vdots & 0 & I & \cdots & \vdots \\
    \vdots & \vdots & \ddots & \ddots & \vdots \\
    0 & \cdots & \cdots & 0 & I
\end{pmatrix}
\]

\[
\times \begin{pmatrix}
    \mathcal{X}_{m-1} \\
    \vdots \\
    \mathcal{X}_{m+n-2}
\end{pmatrix} + \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1})
\]

\[\equiv G(\mathcal{Y}_{m-1}), \quad (6)\]

where \( \mathcal{X}_m = \phi(\mathcal{X}_{m-1}, \mathcal{X}_{m-n}) \). Thus, the Jacobian of \( G(\mathcal{Y}_{m-1}) \) is given by

\[
DG(\mathcal{Y}_{m-1}) = \begin{pmatrix}
    0 & I & \cdots & \cdots & 0 \\
    \vdots & \ddots & \ddots & \ddots & \vdots \\
    \vdots & \ddots & \ddots & \ddots & \vdots \\
    0 & \cdots & \cdots & 0 & I
\end{pmatrix}
\]

\[D_y \phi \quad \begin{pmatrix}
    0 & \cdots & \cdots & 0 & D_y \phi
\end{pmatrix} \quad \begin{pmatrix}
    0 & \cdots & \cdots & 0 & 0
\end{pmatrix}, \quad (7)\]

where

\[
D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1}) = \begin{pmatrix}
    0 & \cdots & \cdots & 0 & D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1})
\end{pmatrix}, \quad (8)\]

\[
D_y F^{m+n-1} = (D\mathcal{Y}) \begin{pmatrix}
    0 & \cdots & \cdots & 0 & D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1})
\end{pmatrix}, \quad (7)\]

and,

\[
D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1}) = \begin{pmatrix}
    0 & \cdots & \cdots & 0 & D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1})
\end{pmatrix}, \quad (8)\]

\[
D_y F^{m+n-1} = (D\mathcal{Y}) \begin{pmatrix}
    0 & \cdots & \cdots & 0 & D_y \phi(\mathcal{X}_{m+n-2}, \mathcal{X}_{m-1})
\end{pmatrix}, \quad (7)\]

Eqs. (3) and (5) are to be readily expanded to adaptive time step for improving the accuracy if necessary. If the delayed term \( \lambda = 0, D_y \phi \) equals to zero. The eigenvalues of the Jacobian of \( G^m(\mathcal{Y}_0) \) becomes the eigenvalues of \( D_y \phi \), which agrees with the conventional definition of the Lyapunov exponents.

Fig. 4 shows the three Lyapunov exponents \( \beta_1 \) versus \( b \) when \( a = 1.5I_{th}, \tau = 0.75T, \beta = 0.035 \), and \( f_0 = 1/2f_0 \). Note that the second and the third Lyapunov exponent are all negative. \( \beta_1 \approx 0 \) when \( b \in (0, 0.35) \). This implies a nonchaotic quasi two-period attractor which agrees with the results from Poincaré maps. Because at least one Lyapunov exponent of a chaotic system must be positive, chaotic behavior can be established in regions where one positive Lyapunov exponent is shown in the figure. The system also has a chaotic window for \( b \in (0.364, 0.386) \), therefore, in this region there is no positive Lyapunov exponent.

In conclusion, it is proposed that a delayed-feedback technique is used to achieve route to chaos in a quantum-well laser diodes at relatively low bias and small modulation depth. Quasi-periodicity route to chaos can be visualized by the bifurcation diagram and Poincaré map, and further be supported by the calculation of Lyapunov exponents for the delay differential rate equation.
References


